

Geometry Exercises IV

1. We convert the vector field T^a into a density of weight +1 by multiplying through by the scalar density $\sqrt{-g}$. Then, Stokes' theorem (7.19) reads

$$\oint_{\partial\Omega} \sqrt{-g} T^a ds_a = \int_{\Omega} \partial_a (\sqrt{-g} T^a) d\Omega$$

Using the Leibniz property of the derivative on the right, we have

$$\begin{aligned} \partial_a (\sqrt{-g} T^a) &= \frac{1}{2} (-g)^{-1/2} \cdot -\partial_a g \cdot T^a + \sqrt{-g} \partial_a T^a \\ &= -\frac{1}{2} (-g)^{-1/2} \cdot 2g T^b_{ba} T^a + \sqrt{-g} \partial_a T^a \\ &= \sqrt{-g} (\partial_a T^a + T^b_{ba} T^a) = \sqrt{-g} \nabla_a T^a \end{aligned}$$

Here, we have used (7.9) to calculate $\partial_a g$ and (6.22) to form the covariant derivative. The result follows immediately.

2. The wedge product (4.10) of three 1-forms generalizes immediately to the p -fold wedge product as the alternating sum of tensor products:

$$\tilde{r}^1 \wedge \dots \wedge \tilde{r}^p := \sum_{\pi} (-1)^{|\pi|} \tilde{r}^{\pi(1)} \otimes \dots \otimes \tilde{r}^{\pi(p)}$$

The sum here is over the permutation group on p symbols.

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Any p -form can be written as a linear combination of such elementary wedge products using a basis \tilde{w}^α . The key point is the total anti-symmetry of its components:

$$\begin{aligned}
 \tilde{p} &= \sum_{\alpha} p_{\alpha_1, \dots, \alpha_p} \tilde{w}^{\alpha_1} \otimes \dots \otimes \tilde{w}^{\alpha_p} \\
 &= \sum_{\alpha} P[\alpha_1, \dots, \alpha_p] \tilde{w}^{\alpha_1} \otimes \dots \otimes \tilde{w}^{\alpha_p} \\
 &:= \sum_{\alpha} \frac{1}{p!} \sum_{\pi} (-1)^{\pi} p_{\alpha_{\pi(1)}, \dots, \alpha_{\pi(p)}} \cdot \tilde{w}^{\alpha_1} \otimes \dots \otimes \tilde{w}^{\alpha_p} \\
 &= \frac{1}{p!} \sum_{\alpha} \sum_{\pi} (-1)^{\pi} p_{\alpha_1, \dots, \alpha_p} \cdot \tilde{w}^{\alpha_{\pi^{-1}(1)}} \otimes \dots \otimes \tilde{w}^{\alpha_{\pi^{-1}(p)}} \\
 &= \frac{1}{p!} \sum_{\alpha} p_{\alpha_1, \dots, \alpha_p} \tilde{w}^{\alpha_1} \wedge \dots \wedge \tilde{w}^{\alpha_p}
 \end{aligned}$$

Here, we have renamed indices in the penultimate step, and noted that the sum over permutations π in the last step is equal to the sum over their inverses π^{-1} . Thus, we can calculate

$$\begin{aligned}
 \tilde{p} \wedge \tilde{q} &= \frac{1}{p!q!} \sum_{\alpha} p_{\alpha_1, \dots, \alpha_p} q_{\alpha_{p+1}, \dots, \alpha_{p+q}} \tilde{w}^{\alpha_1} \wedge \dots \wedge \tilde{w}^{\alpha_{p+q}} \\
 &= \frac{1}{p!q!} \sum_{\alpha} P[\alpha_1, \dots, \alpha_p, \alpha_{p+1}, \dots, \alpha_{p+q}] \tilde{w}^{\alpha_1} \wedge \dots \wedge \tilde{w}^{\alpha_{p+q}} \\
 &= \frac{1}{(p+q)!} \sum_{\alpha} (p \wedge q)_{\alpha_1, \dots, \alpha_{p+q}} \tilde{w}^{\alpha_1} \wedge \dots \wedge \tilde{w}^{\alpha_{p+q}}
 \end{aligned}$$

The first pair of equalities comes from the definition of the $(p+q)$ -fold wedge product of 1-forms and the total antisymmetry of that product in the α indices. The last equality is the result above applied to the

$(p+q)$ -form $\tilde{p} \wedge \tilde{q}$. The result then follows by taking components on both sides.

3 We have

$$\begin{aligned}
 (\tilde{B} \wedge \tilde{\alpha})(\tilde{\xi}) &:= \frac{1}{(p+q-1)!} \tilde{\xi}^i (B \wedge \alpha)_{ij \dots k} \tilde{w}^j \wedge \dots \wedge \tilde{w}^k \\
 &= \frac{1}{(p+q-1)!} \tilde{\xi}^i \frac{(p+q)!}{p!q!} B_{[ij \dots e} \alpha_{mn \dots k]} \tilde{w}^j \wedge \dots \wedge \tilde{w}^k \\
 &:= \frac{p+q}{p!q!} \tilde{\xi}^i \left(\frac{p}{p+q} B_{i[j \dots e} \alpha_{mn \dots k]} \right. \\
 &\quad \left. + (-1)^p \frac{q}{p+q} B_{[j \dots em} \alpha_{i]n \dots k]} \right) \tilde{w}^j \wedge \dots \wedge \tilde{w}^k \\
 &:= \frac{1}{p!q!} \left(p B(\tilde{\xi})_{[j \dots e} \alpha_{mn \dots k]} \right. \\
 &\quad \left. + (-1)^p q B_{[j \dots em} \alpha(\tilde{\xi})_{n \dots k]} \right) \tilde{w}^j \wedge \dots \wedge \tilde{w}^k \\
 &= \frac{1}{p!q!} \left(p \cdot (p-1)! q! \tilde{B}(\tilde{\xi}) \wedge \tilde{\alpha} + (-1)^p q \cdot p! (q-1)! \tilde{B} \wedge \tilde{\alpha}(\tilde{\xi}) \right) \\
 &= \tilde{B}(\tilde{\xi}) \wedge \tilde{\alpha} + (-1)^p \tilde{B} \wedge \tilde{\alpha}(\tilde{\xi})
 \end{aligned}$$

In the third equality, we have noted that, in the average over permutations, there are p places where the i index can appear on B and q on α . In each case, we have used antisymmetry to move the i index to the first position of the form. We have used (4.13) in the fourth equality, and the first expression for $\tilde{p} \wedge \tilde{q}$ from the last problem in the C.C.+h.

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4 a) Doing a cofactor expansion on the first row of A gives

$$\det A = \sum_{i=1}^n A^{1i} \cdot (-1)^i \cdot \det A^{\hat{1}\hat{i}},$$

where $A^{\hat{1}\hat{i}}$ is the cofactor matrix with the first row and the i^{th} column deleted. Meanwhile, we have

$$\begin{aligned} \varepsilon_{ij\dots k} A^{1i} A^{2j} \dots A^{nk} \\ := \sum_{i=1}^n A^{1i} \cdot (-1)^i \varepsilon_{j\dots k}^{(\uparrow)} A^{2j} \dots A^{nk} \end{aligned}$$

Here, $\varepsilon_{j\dots k}^{(\uparrow)}$ denotes the alternating symbol with $n-1$ indices taking all values from 1 to n except i . The $(-1)^i$ arises because

$$\varepsilon_{1\dots i\dots n} = (-1)^i \varepsilon_{i1\dots \uparrow \dots n} = \varepsilon_{i1\dots \uparrow \dots n}^{(\uparrow)}$$

Thus, the determinant and the ε -expression have the same recurrence relation, and the result follows by induction.

b) The tensor

$$B^{ab\dots c} := \varepsilon_{ij\dots k} A^{ai} A^{bj} \dots A^{ck}$$

is totally anti-symmetric and has $B^{1\dots n} = \det A$. When we contract it with $\varepsilon_{ab\dots c}$, we get a sum of identical terms over the $n!$ permutations of indices.

c) The orthonormal basis co-vectors \tilde{w}^α have expansions

$$\tilde{w}^\alpha = w_i^\alpha \tilde{d}x^i$$

in the coordinate basis. Thus,

$$\begin{aligned} \tilde{w} &:= \tilde{w}^1 \wedge \tilde{w}^2 \wedge \dots \wedge \tilde{w}^n \\ &= w_i^1 w_j^2 \dots w_k^n \tilde{d}x^i \wedge \tilde{d}x^j \wedge \dots \wedge \tilde{d}x^k \end{aligned}$$

The wedge product here is totally anti-symmetric in the indices $1 \dots k$, so

$$\tilde{w} = \det(w_i^\alpha) \tilde{d}x^i \wedge \tilde{d}x^j \wedge \dots \wedge \tilde{d}x^k$$

Meanwhile, we have

$$g_{ab} = \eta_{\alpha\beta} w_a^\alpha w_b^\beta \quad \text{with } \eta_{\alpha\beta} = \pm 1, \text{ diagonal}$$

because the \tilde{w}^α are orthonormal. Taking coordinate components and a determinant,

$$\begin{aligned} \det(g_{ij}) &= \det(w_i^\alpha \eta_{\alpha\beta} w_j^\beta) \\ &= \det(w_i^\alpha) \det(\eta_{\alpha\beta}) \det(w_j^\beta) \\ &= \pm \det(w_i^\alpha)^2 \end{aligned}$$

Thus, $\det(w_i^\alpha) = \sqrt{|\det(g_{ij})|}$, and the result follows.

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5 a) Using the axioms on p. 134, we have

$$d(fdg) = df \wedge dg + (-1)^0 f ddg = df \wedge dg$$

b) It follows that

$$\begin{aligned} d\alpha &= \frac{1}{p!} d(\alpha_{i_1 \dots i_p} dx^{i_1} \wedge \dots \wedge dx^{i_p}) \\ &= \frac{1}{p!} (d\alpha_{i_1 \dots i_p} \wedge dx^{i_1} \wedge \dots \wedge dx^{i_p} \\ &\quad + \alpha_{i_1 \dots i_p} d dx^{i_1} \wedge \dots \wedge dx^{i_p} - \dots \\ &\quad \pm \alpha_{i_1 \dots i_p} dx^{i_1} \wedge \dots \wedge d dx^{i_p}) \\ &= \frac{1}{p!} d\alpha_{i_1 \dots i_p} \wedge dx^{i_1} \wedge \dots \wedge dx^{i_p} \\ &= \frac{1}{p!} \partial_k \alpha_{i_1 \dots i_p} dx^k \wedge dx^{i_1} \wedge \dots \wedge dx^{i_p} \end{aligned}$$

Meanwhile, we also have

$$d\alpha = \frac{1}{(p+1)!} (d\alpha)_{k i_1 \dots i_p} dx^k \wedge dx^{i_1} \wedge \dots \wedge dx^{i_p}$$

The result follows immediately.

6 We have

$$(\vec{\nabla} \cdot \vec{\nabla} \times \vec{a}) \tilde{w} = d * (\vec{\nabla} \times \vec{a}) = d * (* da) = dda = 0$$

$$\vec{\nabla} \times \vec{\nabla} a = * d (\vec{\nabla} a) = * dda = 0$$

7 A curl-free vector field satisfies

$$0 = \vec{\nabla} \times \vec{a} = *da \Rightarrow da = 0$$

$$\Rightarrow a = db \Rightarrow \vec{a} = \vec{\nabla} b$$

A divergence-free vector field satisfies

$$0 = (\vec{\nabla} \cdot \vec{a}) \tilde{\omega} = d*a$$

$$\Rightarrow *a = db \Rightarrow a = *db \Rightarrow \vec{a} = \vec{\nabla} \times \vec{b}$$

8 a) The divergence is defined by

$$(\operatorname{div}_{\tilde{\omega}} \vec{a}) \tilde{\omega} = \tilde{d}(\tilde{\omega}(\vec{a}))$$

But we have

$$\tilde{\omega}(\vec{a}) = f \cdot (\tilde{d}x^1 \wedge \dots \wedge \tilde{d}x^n)(\vec{a})$$

$$= \sum_{i=1}^n f \cdot (-1)^{i-1} \tilde{d}x^1 \wedge \dots \wedge \tilde{d}x^i(\vec{a}) \wedge \dots \wedge \tilde{d}x^n$$

$$= \sum_{i=1}^n f \tilde{a}^i (-1)^{i-1} \tilde{d}x^1 \wedge \dots \wedge \widehat{\tilde{d}x^i} \wedge \dots \wedge \tilde{d}x^n$$

$$\Rightarrow d(\tilde{\omega}(\vec{a})) = \sum_{i,j} \partial_j (f \tilde{a}^i) (-1)^{i-1} \tilde{d}x^j \wedge \tilde{d}x^1 \wedge \dots \wedge \widehat{\tilde{d}x^i} \wedge \dots \wedge \tilde{d}x^n$$

The notation $\widehat{\tilde{d}x^i}$ here means that $\tilde{d}x^i$ is excluded in the product. Thus, we must have $j=i$ to get a non-zero result, and we must move $\tilde{d}x^j = \tilde{d}x^i$ past $i-1$ 1-forms in the product. The result follows.

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b) Here, we use the determinant formula

$$ds^2 = dr^2 + r^2 d\theta^2 + r^2 \sin^2 \theta d\phi^2$$

$$\Rightarrow \det g = \begin{vmatrix} 1 & & \\ & r^2 & \\ & & r^2 \sin^2 \theta \end{vmatrix} = r^4 \sin^2 \theta$$

$$\Rightarrow \tilde{\omega} = |\det g|^{1/2} dr \wedge d\theta \wedge d\phi = r^2 \sin \theta dr \wedge d\theta \wedge d\phi$$

and

$$\begin{aligned} \operatorname{div} \bar{z} &= \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial r} (r^2 \sin \theta \bar{z}^r) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} (r^2 \sin \theta \bar{z}^\theta) \\ &\quad + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \phi} (r^2 \sin \theta \bar{z}^\phi) \\ &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \bar{z}^r) + \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (\sin \theta \bar{z}^\theta) + \frac{\partial}{\partial \phi} \bar{z}^\phi \end{aligned}$$

9 a) We have first of all that

$$(*\bar{z})_{j \dots k} := \frac{1}{k!} \bar{z}^i w_{ij \dots k} = (\tilde{\omega}(\bar{z}))_{j \dots k}$$

We also have $*w = 1$, so

$$\operatorname{div} \tilde{\omega} \bar{z} = *(\operatorname{div} \tilde{\omega} \bar{z}) = * \tilde{d} (\tilde{\omega}(\bar{z})) = * \tilde{d} * \bar{z}$$

b) If F is a p -vector, $*F$ is an $(n-p)$ -form, $d*F$ is an $(n-p+1)$ -form, and $*d*F$ is an $[n-(n-p+1)]$ -vector, which is a $(p-1)$ -vector.

To calculate its components, we write

$$\begin{aligned}
(*d*F)^{i\dots j} &:= \frac{1}{(n-p+1)!} w^{kl\dots mi\dots j} (d*F)_{kl\dots m} \\
&:= \frac{1}{(n-p+1)!} w^{kl\dots mi\dots j} \cdot (n-p+1) \partial_{[k} (*F)_{l\dots m]} \\
&:= \frac{1}{(n-p)!} w^{kl\dots mi\dots j} \partial_k \left(\frac{1}{p!} w_{ab\dots c l\dots m} F^{ab\dots c} \right) \\
&= \frac{1}{(n-p)! p!} w^{kl\dots mi\dots j} w_{ab\dots c l\dots m} \partial_k F^{ab\dots c}
\end{aligned}$$

Here, we have used the fact that the components of $w_{i\dots j} = \epsilon_{i\dots j}$ are constants ± 1 or 0 . We now move the $n-p$ indices $l\dots m$ past the p indices $ab\dots c$ in the second w , and past the one index k in the first, and then use ϵ - δ identities

$$\begin{aligned}
&w^{kl\dots mi\dots j} w_{ab\dots c l\dots m} = \\
&= (-1)^{n-p} w^{l\dots m ki\dots j} \cdot (-1)^{p(n-p)} w_{l\dots m ab\dots c} \\
&= (-1)^{(n-p)(p+1)} \delta_{l\dots m ab\dots c}^{ki\dots j} \\
&= (-1)^{(n-p)(p-1)} (n-p)! \delta_{ab\dots c}^{ki\dots j} \\
&= (-1)^{(n-p)(p-1)} (n-p)! p! \delta_{[a}^k \delta_b^i \dots \delta_{c]}^j
\end{aligned}$$

Thus, we find

$$\begin{aligned}
(*d*F)^{i\dots j} &= (-1)^{(n-p)(p-1)} \delta_{[a}^k \delta_b^i \dots \delta_{c]}^j \partial_k F^{ab\dots c} \\
&= (-1)^{(n-p)(p-1)} \partial_k F^{ki\dots j}
\end{aligned}$$

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c) In this case, we have

$$w_{i\dots j} = f \varepsilon_{i\dots j} \quad \text{and} \quad w^{i\dots j} = f^{-1} \varepsilon^{i\dots j}$$

Making the appropriate changes in the calculation above, we have an extra f inside the derivative and an extra f^{-1} outside. Thus, we find

$$(\operatorname{div}_{\tilde{w}} F)^{i\dots j} = f^{-1} (f F^{ki\dots j})_{,k}$$